

Community Metrics Report

Tully Foote Reporting on July 2014

Comparisons are to August 2013 Report

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Source: Metrics categories borrowed from Dawn Foster of MeeGo: http://wiki.meego.com/Metrics

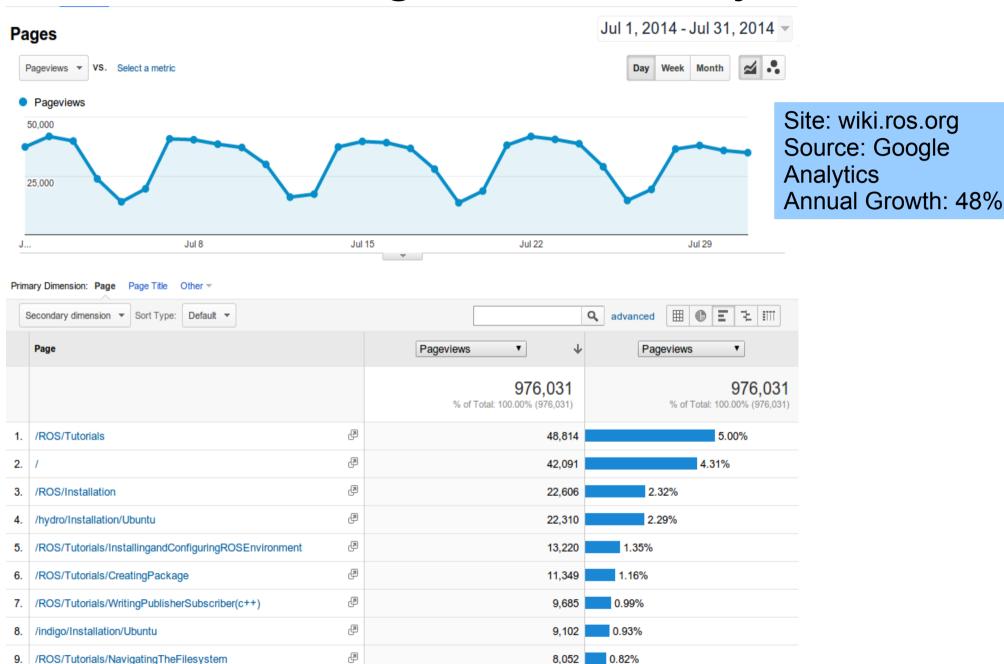
Awareness Metrics

Discovering the community, learning more about it (potential community members)

ros.org: Visitors & Page Views

wiki.ros.org Visitors: July 2014

0.69%

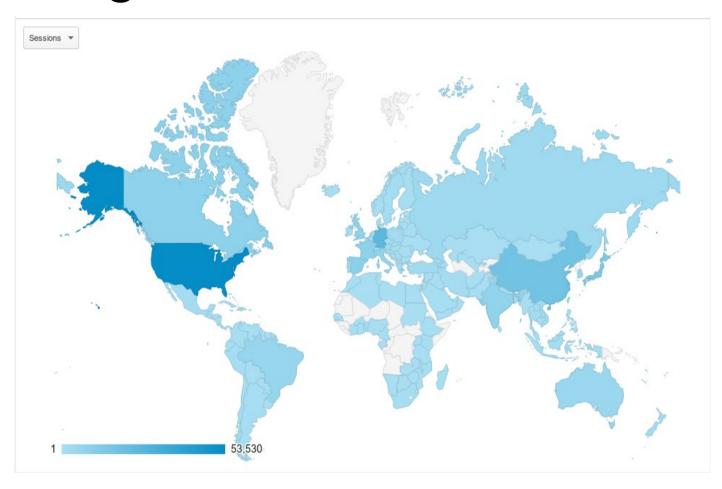


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/hydro/Installation

wiki.ros.org visitor locations:

1.	W	United States	53,530	(23.40%)
2.		Germany	25,133	(10.99%)
3.	**	China	17,812	(7.79%)
4.	•	Japan	14,619	(6.39%)
5.	2	Spain	9,192	(4.02%)
6.	•	Canada	8,611	(3.76%)
7.		France	8,399	(3.67%)
8.	10 10 20 20	United Kingdom	7,434	(3.25%)
9.	0	India	7,360	(3.22%)
10.		Italy	6,623	(2.90%)
11.	•	Brazil	5,837	(2.55%)
12.	(0)	South Korea	4,988	(2.18%)
13.	**	Australia	4,828	(2.11%)
14.	Ço.	Singapore	4,688	(2.05%)
15.		Russia	3,534	(1.54%)
16.	0	Portugal	3,194	(1.40%)
17.		Netherlands	2,556	(1.12%)
18.	•	Switzerland	2,454	(1.07%)
19.		Poland	2,279	(1.00%)
20.		Taiwan	2,252	(0.98%)



Source: Google Analytics Site: wiki.ros.org in August

Public wiki.ros.org Mirrors

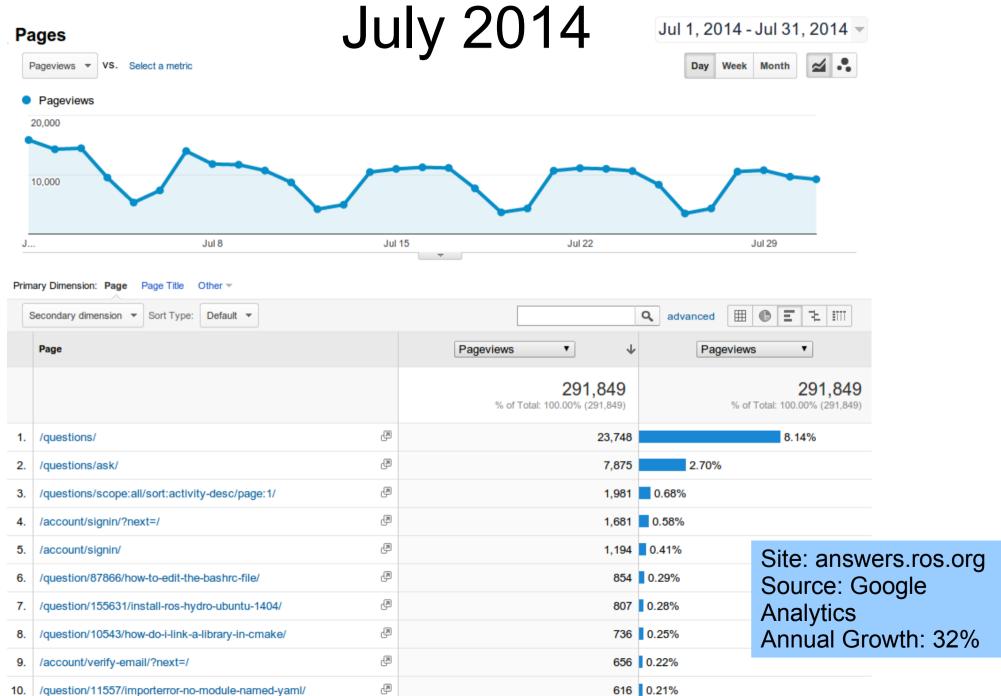
- Asia:
 - Singapore
 - Sun Yat-Sen Univerity, China
 - Shanghai, China
 - Tokyo, Japan
- Europe:
 - Ireland
 - Freiburg, Germany
 - · Barcelona, Catalonia
- North America:
 - College Park, Maryland
 - Austin, Texas
- South America
 - · Sao Paulo, Brazil

This report does not include data from these mirrors.

Source: http://wiki.ros.org/Mirrors

answers.ros.org: visitors

answers.ros.org visitors:



Membership Metrics

Taking the time to sign up and join the community (passive and active community members)

Site & list membership

- ros-users@lists.ros.org subscribers:
 - 1758 (12% increase)
- wiki.ros.org users:
 - 4056 (20% increase)
- answers.ros.org users:
 - 8572 (48% increase)

Sources: MailMan, MoinMoin, askbot

Sampled: 8/18/2014

Engagement Metrics

Interacting with other community members (active community members)

wiki.ros.org: activity

- Wiki pages:
 - 14,697 (35% decrease)
- Wiki page edits:
 - 33.1 / day (averaged over July, 5% increase)
- Wiki page views:
 - 31,483 / day (averaged over July, 20% increase)

Source: MoinMoin, Google Analyics (sampled 2014-08-18)

answers.ros.org: activity

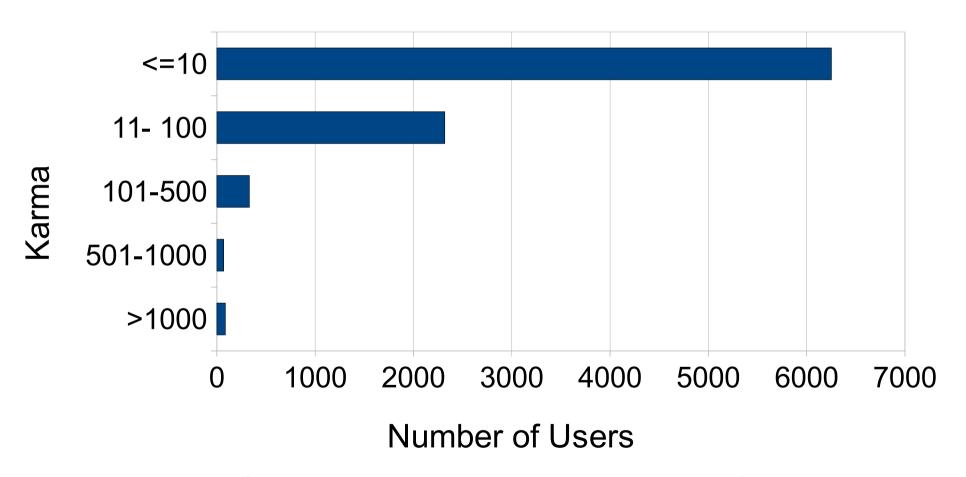
- Total questions:
 - 18,144 (38% increase)
- Unanswered questions:
 - 5,884 (32% increase)
- New questions in July:
 - 524 (16.9 / day, 33% increase)

Source: Askbot

Sampled: 2014-08-18

answers.ros.org Karma

Sampled 2014-08-18



Histogram of users by karma. Users get karma points for having answers upvoted (+10) or accepted (+15) and for accepting someone else's answer (+2).

Code Metrics

Engaging with the ROS project at a code level (developers and users)

Binary Downloads – July 2014

- Total Unique IP addresses downloading .deb files:
 - 49,153 (343 % increase)
- Total downloads of .deb packages:
 - 3,570,374 (123% increase)
- Unique package names downloaded as .deb files:
 - 4,000 (54% increase)
- Number of unique versions of .deb packages downloaded:
 - 46,056 (41 % increase)

Source: Apache2, counting only downloads from the main repository (not the testing repository, shadow-fixed)

Top 40 Downloaded Packages Direct downloads from packages.ros.org - July 2014

python-catkin-pkg	17308	ros-hydro-depth-image-proc	7177
python-rosdep	16063	ros-hydro-rqt-gui-cpp	7169
python-rospkg	14268	ros-hydro-rqt-common-plugins	7148
python-wstool	10031	ros-hydro-geometry-experimental	7138
ros-hydro-kdl-conversions	7908	ros-hydro-bondpy	7129
ros-hydro-orocos-kdl	7880	ros-hydro-nodelet-core	7126
ros-hydro-tf-conversions	7862	ros-hydro-tf2-geometry-msgs	7113
ros-hydro-python-orocos-kdl	7850	ros-hydro-bond-core	7099
ros-hydro-nodelet	7836	ros-hydro-tf2-kdl	7088
ros-hydro-kdl-parser	7781	ros-hydro-rqt-image-view	7085
ros-hydro-bond	7779	ros-hydro-voxel-grid	7065
ros-hydro-smclib	7768	ros-hydro-move-base-msgs	7060
ros-hydro-bondcpp	7746	ros-hydro-nodelet-tutorial-math	7055
ros-hydro-nodelet-topic-tools	7681	ros-hydro-image-view	7054
ros-hydro-eigen-conversions	7665	ros-hydro-map-server	7048
python-rosdistro	7641	ros-hydro-robot	7044
ros-hydro-robot-state-publisher	7576	ros-hydro-robot-model	7043
ros-hydro-pcl-ros	7459	ros-hydro-common-tutorials	7034
ros-hydro-geometry	7365	ros-hydro-amcl	7029
ros-hydro-image-proc	7225	ros-hydro-nav-core	7007

Public Debian Package Mirrors

- Sun Yat-Sen University(China)
- Shanghai(China)
- Ireland
- Freiburg (Germany)

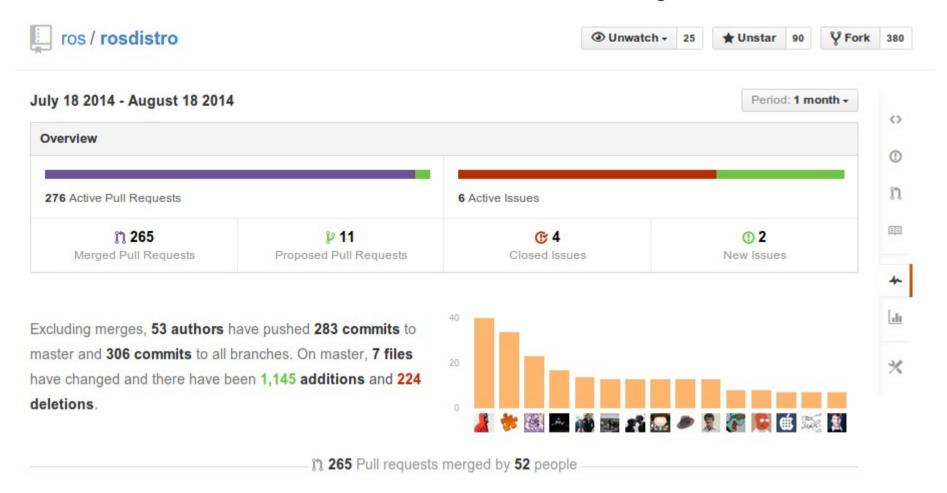
This report does not include data from these mirrors.

Source:

http://wiki.ros.org/ROS/Installation/UbuntuMirrors

- Delft University of Technology (The Netherlands)
- University of Maryland (USA)
- Case Western Reserve University (USA)
- Centro Universitário da FEI (Brazil)

rosdistro activity



The rosdistro http://github.com/ros/rosdistro is the repository where releases are managed and the main index of publicly announced ROS packages. Most pull requests on this repository are requests for indexing or packaging of ROS packages.

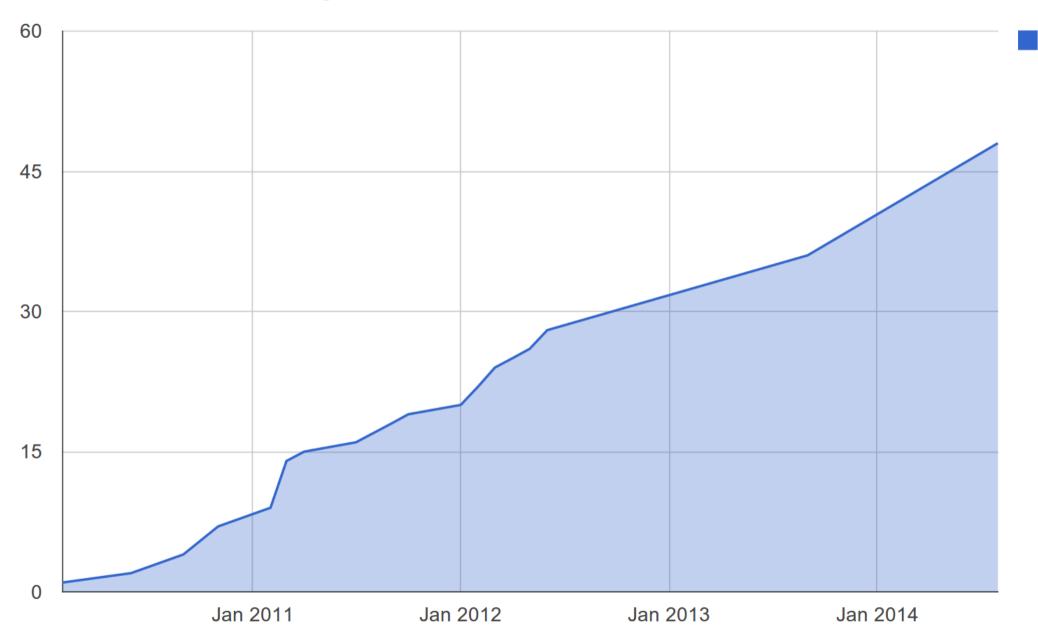
Research use

Number of papers citing "ROS: an open-source Robot Operating System" (Quigley et al., 2009):

1216 (62% increase)

Source: Google Scholar 2014-08-18

Robots listed on wiki.ros.org/Robots



The number of different types of robots available to the community with ROS drivers.

Source: Ken Conley, Tully Foote, wiki.ros.org/Robots