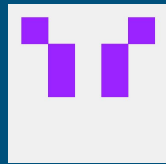


What's Past the End? The Future of ROS One



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Probably not.

I mean, in the long run, definitely no,
you should switch to ROS 2.

Does that mean that everything is working great on ROS 2? Ehhh...

I mean ROS 1 has its problems, but there's a ton of stuff, where you're like, "Wait, you mean they haven't figured out X yet?"

However, ROS 1 has a [ticking clock](#) and will only be supported until 2025.

ros.org

Open Robotics's Software Support

However, ROS 1 has a ticking clock and will only be supported until 2025.

- Buildfarm (prominently) for Ubuntu 20.04
 - rosdistro noetic distribution management
- ... as OR's resources permit

Where does that leave us on newer systems?

How to install ROS1?

What most people do (Ubuntu until focal):

```
$ sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb_release -sc) main" >  
/etc/apt/sources.list.d/ros-latest.list'
```

```
$ curl -s https://raw.githubusercontent.com/ros/rosdistro/master/ros.asc | apt-key add -
```

```
$ apt update
```

```
$ apt install ros-noetic-desktop-full
```

How to install ROS1?

Debian GNU/Linux:

```
$ apt install ros-desktop-full
```

Arch Linux (AUR):

```
$ paru -S ros-noetic-desktop-full
```

RoboStack:

```
$ mamba create -n ros_env python=3.9
```

```
$ conda activate ros_env
```

```
$ conda config --env --add channels robostack
```

```
$ mamba install ros-noetic-desktop-full
```

How to install ROS1?

From Source:

```
$ rosinstall_generator \  
  -rostdistro noetic -deps [--upstream-development] \  
  desktop | vcs import
```

```
$ catkin build
```

How to install ROS1?

From Source:

```
$ rosinstall_generator \  
  -rostdistro noetic -deps [--upstream-development] \  
  desktop | vcs import
```

```
$ catkin build
```

```
[build] Summary: 53 of 184 packages succeeded.  
[build] Ignored: None.  
[build] Warnings: 54 packages succeeded with warnings.  
[build] Abandoned: 130 packages were abandoned.  
[build] Failed: 1 packages failed.  
[build] Runtime: 2 minutes and 52.0 seconds total.  
[build] Note: Workspace packages have changed, please re-source setup files to use them.
```

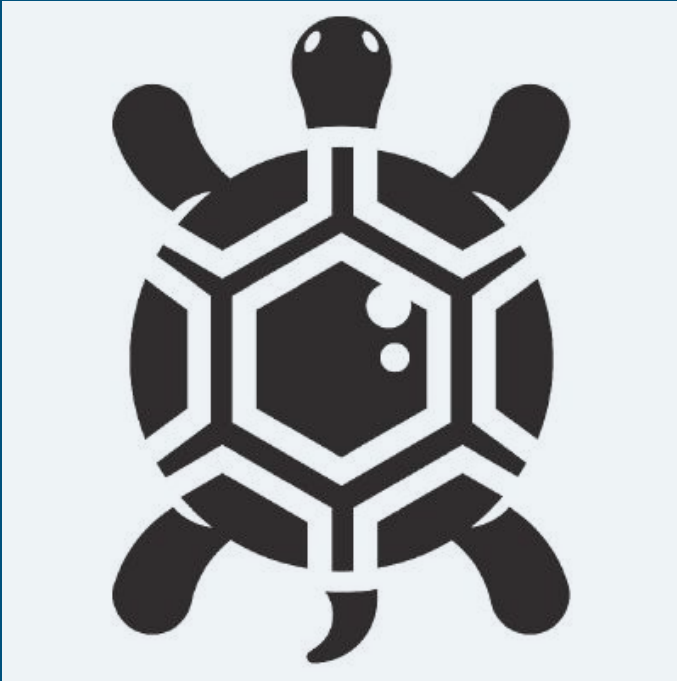
Updated Dependencies

- log4cxx 0.11-0.13
- C++17
- OGRE 1.12
- SIP 5/6
- ...

External packagers either

- Pin their dependencies
 - Keep the 'focal' versions
- Maintain patch sets
 - Distribution-specific overhead

ROS-0 / <https://github.com/ros-o>



- ROS...
 - One
 - Obese Ocadia
 - Obsolete
- Pick your preferred interpretation

ROS-O / <https://github.com/ros-o>

- ROS-O collects patches across packager efforts
- Provide patched source repositories if `noetic-devel` fails to build
- As of today 56+ patched repositories (contributed back to upstream `noetic-devel` where possible)

- Package maintenance is **volunteer effort**
- If you need packages fixed: contribute patches
- If you need packages built: use any distributor and support them