

Edge Impulse & ROS 2 / micro-ROS

Avi Brown



Who am I?

- Electronics engineer at a small agricultural robotics startup
- Side projects with Edge Impulse





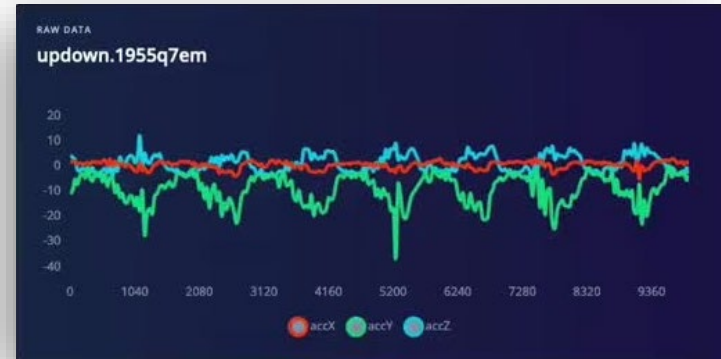
Edge Impulse: Background

- Platform for building machine learning models for memory-constrained devices, supporting every stage of the ML cycle:
 - Data ingest / collection
 - Model design
 - DSP blocks
 - Training
 - Testing
 - Deployment
- **End result:** Open, self-contained, custom library ready for deployment on embedded devices



Data collection

- Direct file upload
 - .csv, .json, image / audio files, etc.
- **Data forwarder**
 - Print raw sensor data to serial
 - CLI tool forwards data directly to Edge Impulse suite...



Dashboard

Devices

Data acquisition

Impulse design

- Create impulse
- Spectral features
- NN Classifier
- Anomaly detection

Retrain model

Live classification

Model testing

Versioning

Deployment

GETTING STARTED

Documentation

Forums

DATA COLLECTED
15m 47sLABELS
5

Collected data



| SAMPLE NAME | LABEL | ADDED | LENGTH |
|--------------------|-------|-----------------------|--------|
| sim.json.1tgtteeae | sim | Feb 03 2021, 16:40:04 | 18s |
| sim.json.1tgg80st | sim | Feb 03 2021, 15:44:08 | 18s |
| sim.json.1tgp2eo7 | sim | Feb 03 2021, 15:23:37 | 9s |
| sim.json.1tgp1na7 | sim | Feb 03 2021, 15:23:13 | 27s |
| sim.json.1tgnlcvs | sim | Feb 03 2021, 14:59:00 | 18s |
| sim.json.1tgnhr7v | sim | Feb 03 2021, 14:57:04 | 27s |
| sim.json.1tgngjbk | sim | Feb 03 2021, 14:56:23 | 9s |
| sim.json.1tglrrld | sim | Feb 03 2021, 14:27:35 | 18s |
| sim.json.1tgkp9oo | sim | Feb 03 2021, 14:08:42 | 18s |
| sim.json.1tgkm5g8 | sim | Feb 03 2021, 14:07:00 | 55s |
| sim.json.1tgkglvl | sim | Feb 03 2021, 14:04:00 | 18s |
| sim.json.1tgkc0au | sim | Feb 03 2021, 14:01:27 | 5s |

Record new data

Device ⓘ

dev1

Label

sim

Sample length (ms.)

10000

Sensor

Sensor with 3 axes (a, b, c)

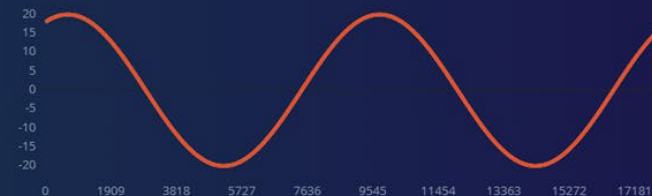
Frequency

11Hz

Start sampling

RAW DATA

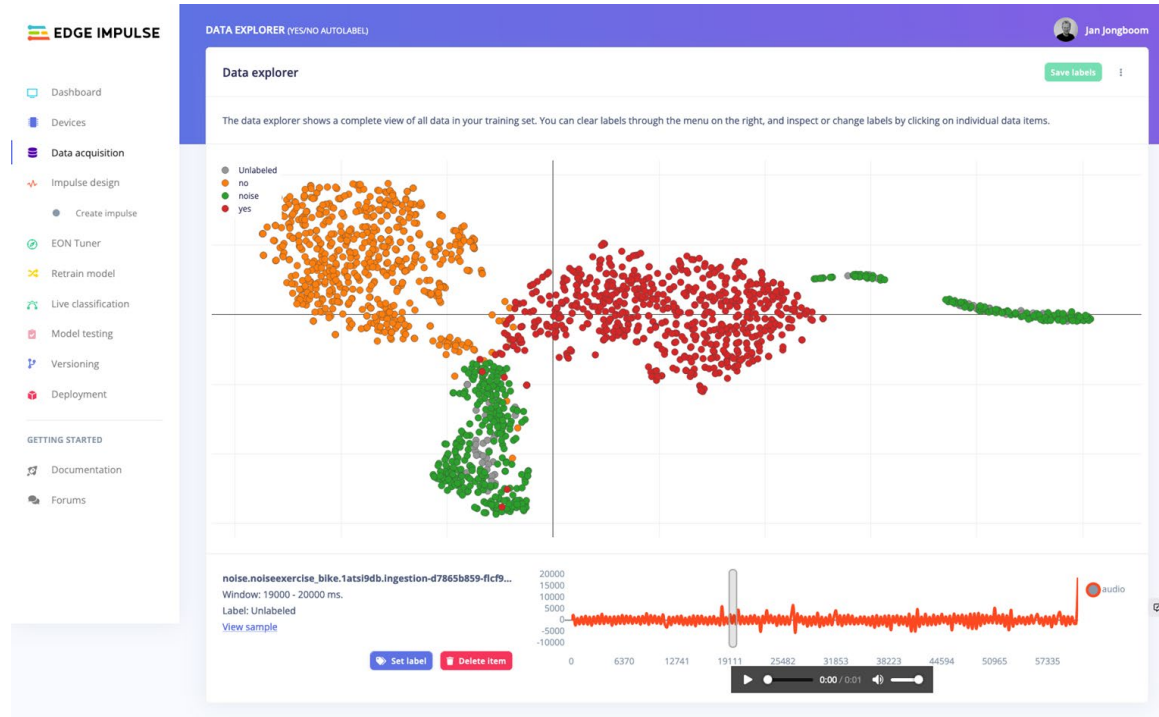
sim.json.1tgtteeae



a b c

Data exploration

- Visualize and clean up datasets



Deploy as you please...

Create library

Turn your impulse into optimized source code that you can run on any device.



C++ library



Arduino library



Cube.MX CMSIS-PACK



WebAssembly



TensorRT library



Ethos-U library



Tensai Flow library



Meta TF Model

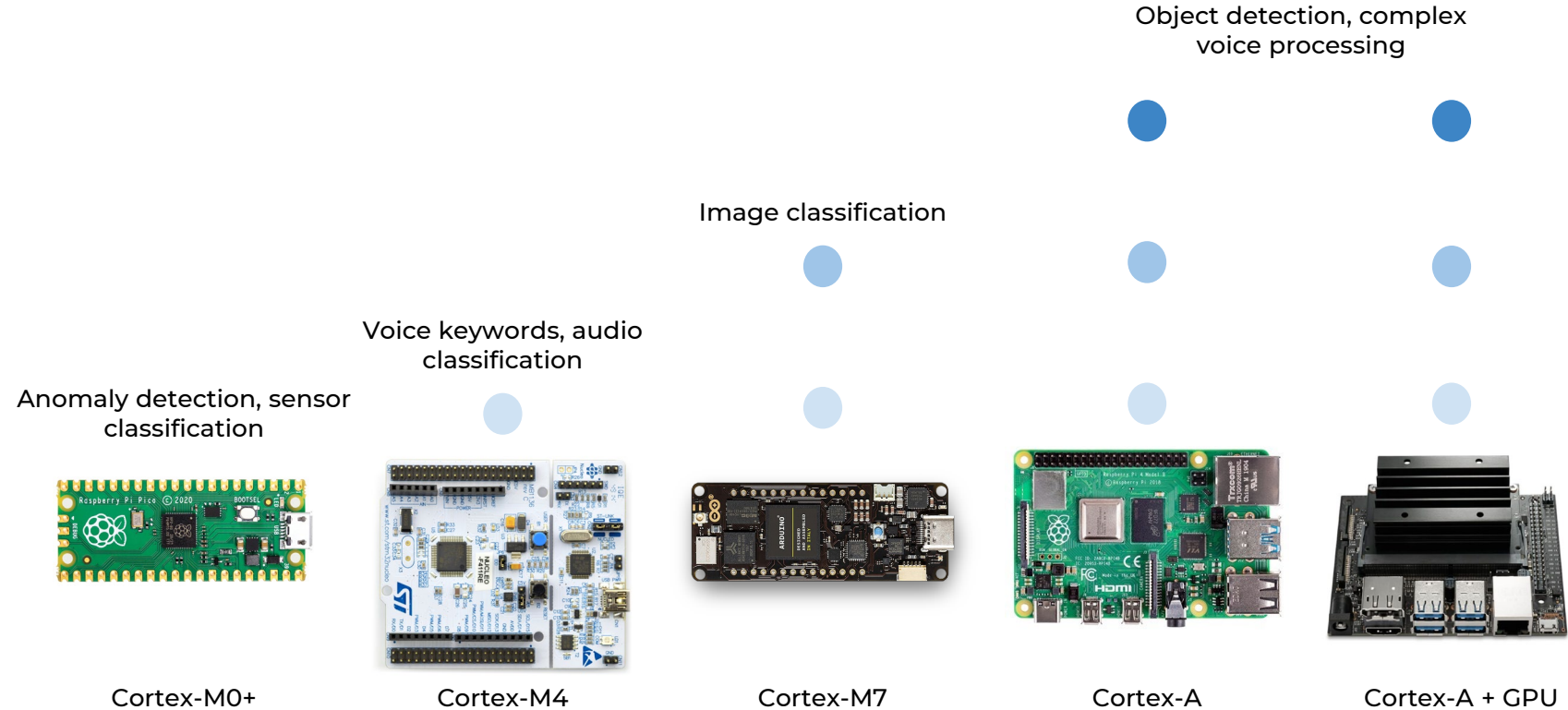


Simplicity Studio
Component



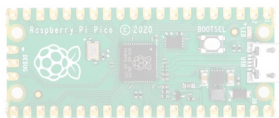
OpenMV library

Hardware vs. capability map



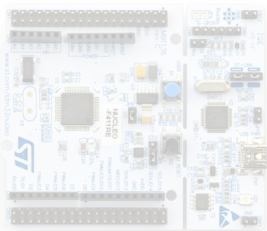
Linux SBCs

Anomaly detection, sensor
classification



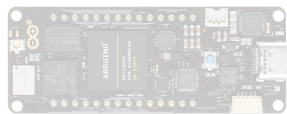
Cortex-M0+

Voice keywords, audio
classification



Cortex-M4

Image classification



Cortex-M7

Object detection, complex
voice processing



Cortex-A



Cortex-A + GPU

Existing ROS 2 + Edge Impulse integrations

- Generic ROS2 publisher + subscriber node for Edge Impulse models
 - Collect data from any sensor, pass through .eim model, publish results
- Nanosaur + ROS2 wrapper for Edge Impulse vision models
 - Raffaello Bonghi, PhD, Giovanni di Dio Bruno, MSc



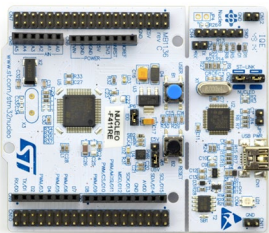
MCUs

Anomaly detection, sensor
classification



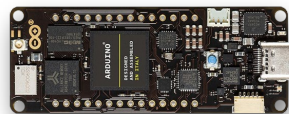
Cortex-M0+

Voice keywords, audio
classification



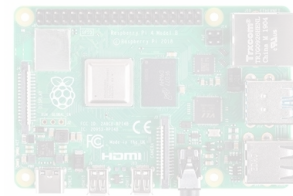
Cortex-M4

Image classification

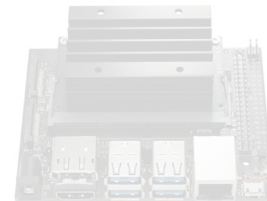


Cortex-M7

Object detection, complex
voice processing



Cortex-A

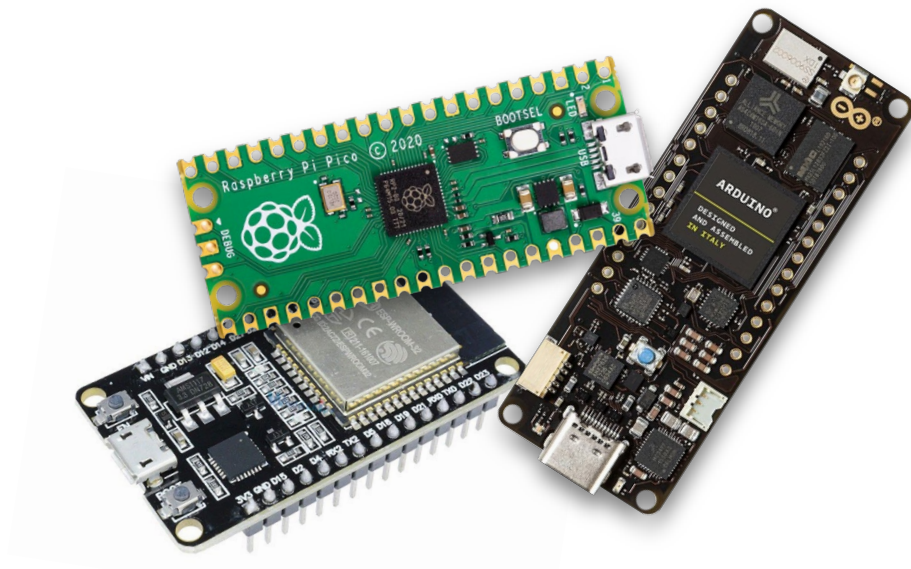


Cortex-A + GPU

micro-ROS

Certain things are better handled by MCUs:

- Hardware interfacing
- Low power
- Real time tasks



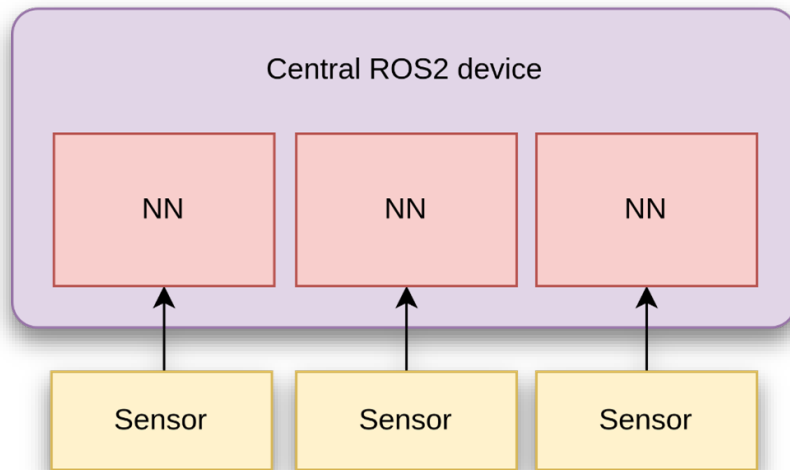
“Edge AI” in robotics

- Inferencing close to the sensor
- Offloading compute from main computer
- OAK-D by Luxonis...



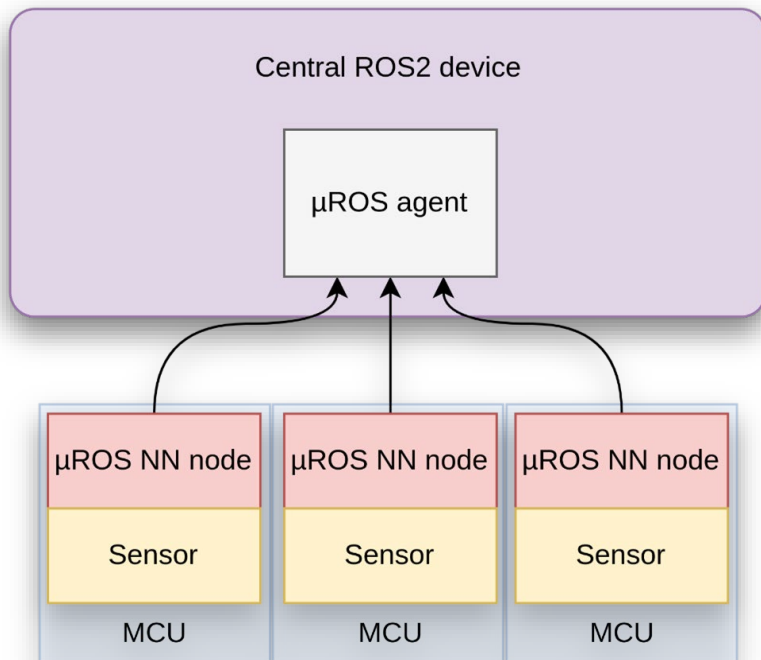
“Traditional” approach to AI in robotics

- Low cost SBCs can quickly become bogged down by multiple NNs running simultaneously



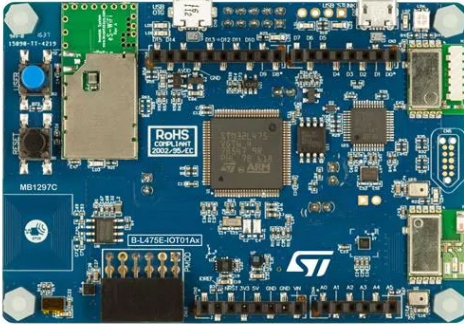
Distributed approach

- By offloading NNs to peripheral MCUs, the central computer can focus on inferences alone



Edge Impulse + micro-ROS

- Growing hardware cross-compatibility



STM32L4 Discovery kit IoT



ESP32



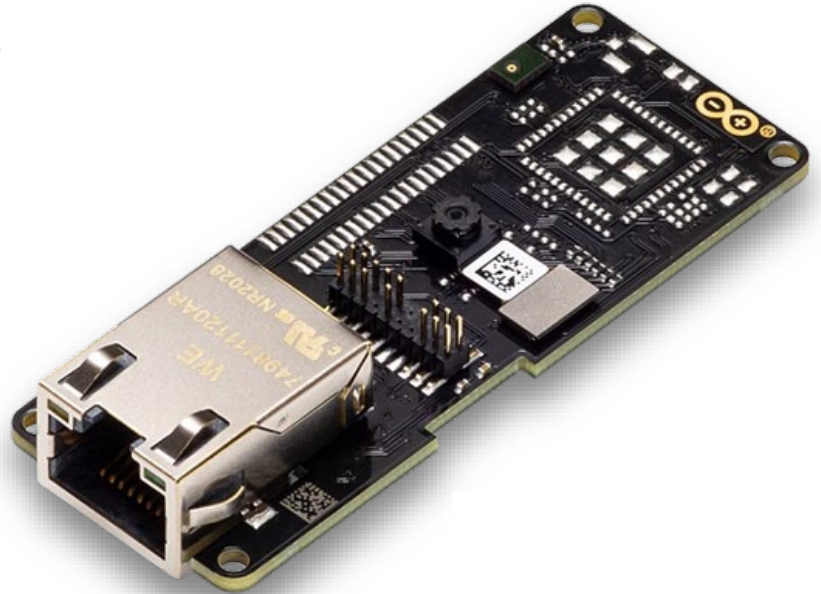
RPi Pico



Arduino Portenta H7

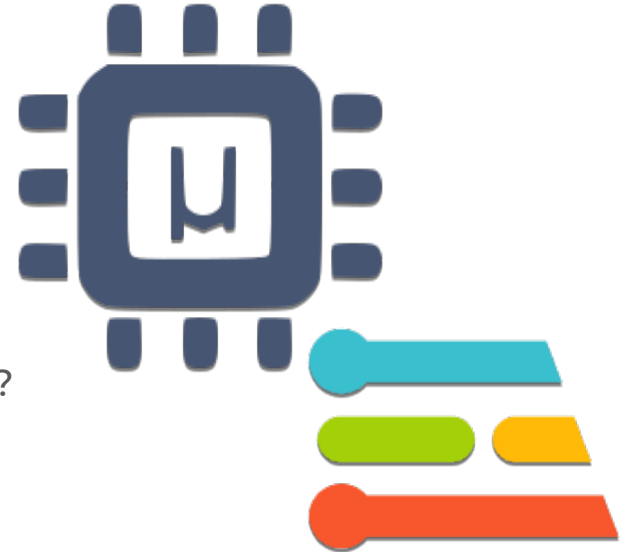
How it's going

- A repo is born...
- Working examples with Portenta H7 + vision shield
- Plans for additional board support



Use cases in robotics

- Add custom “wake-words” / voice commands
- Improve robot’s situational awareness:
 - Terrain recognition
 - Environmental sensor fusion
- Predictive maintenance
 - Motor Current Signal Analysis
 - Mechanical vibration anomaly detection
- Visualisation with rviz2
 - “Markers” based on inference – groovy heatmaps?





Thank you

LinkedIn: **avi-brown**

